# 10.4 NMOS Logic Design

**Reading Assignment:** *974-980*

An alternative to CMOS logic is **NMOS logic.**

**Q:**

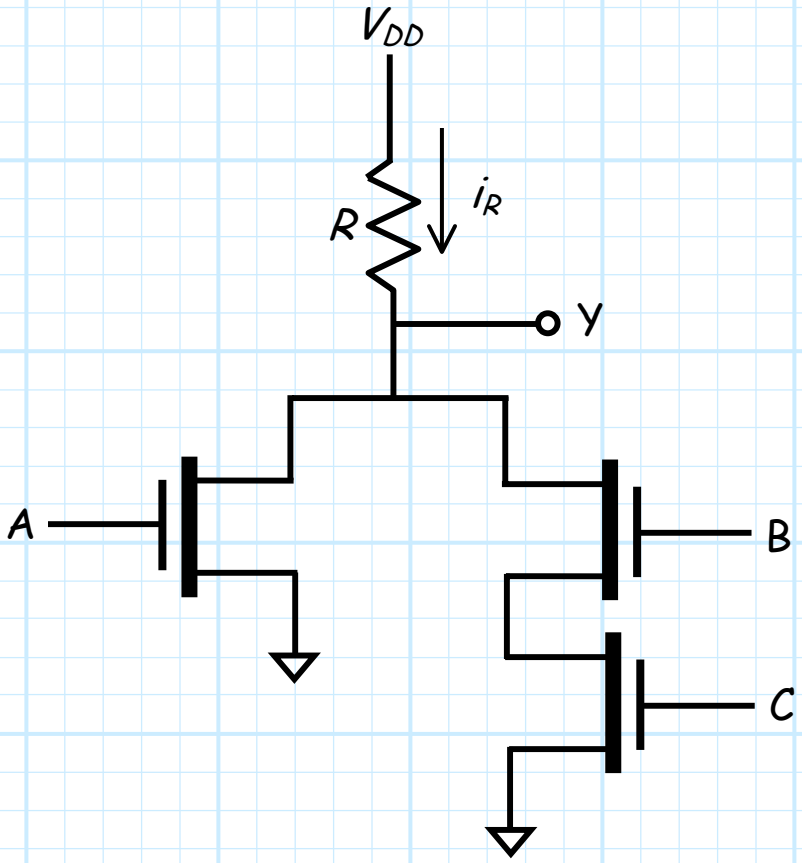
**A:** HO: NMOS Logic Circuits

HO: The Depletion Load

HO: The Pseudo-NMOS Load

# NMOS Logic Circuits

An alternative way to construct a digital logic gate is to simply use a single **large resistor** as the pull-up network!




If the PDN is **open**, no current will flow ($i_R$ =0), and thus there will be **no** voltage drop across the **Pull-Up Resistor** *R*—the output will be high, **just** like before!

**But**, if the PDN **is** conducting, current **will** flow ($i_R \neq 0$), and thus there **will** be a large voltage drop across *R*—the output will be **low** (sort of)!

This method of constructing digital devices is called **NMOS logic** (for hopefully **obvious** reasons!).

**Q:** *Why would we want use NMOS logic?*

**A:** Replacing the PUN with a single resistor greatly **simplifies** and **shrinks** the circuit. For complex gates (i.e., gates with **many** inputs), we can reduce the number of required devices (transistors and resistors) by **nearly half**!

**Q:** *Yikes! This seems to be **a lot** better. Why wouldn't we **always** use NMOS logic?*

**A:** There are **two** really big problems with NMOS logic (at least, when compared to **CMOS**):

1. Since current flows when the output is low, the static power dissipation is **not zero**.

2. Since current flows when the output is low, $V_{OL}$ is **not** equal to its ideal value of **zero** (i.e., $V_{OL} \neq 0$)!

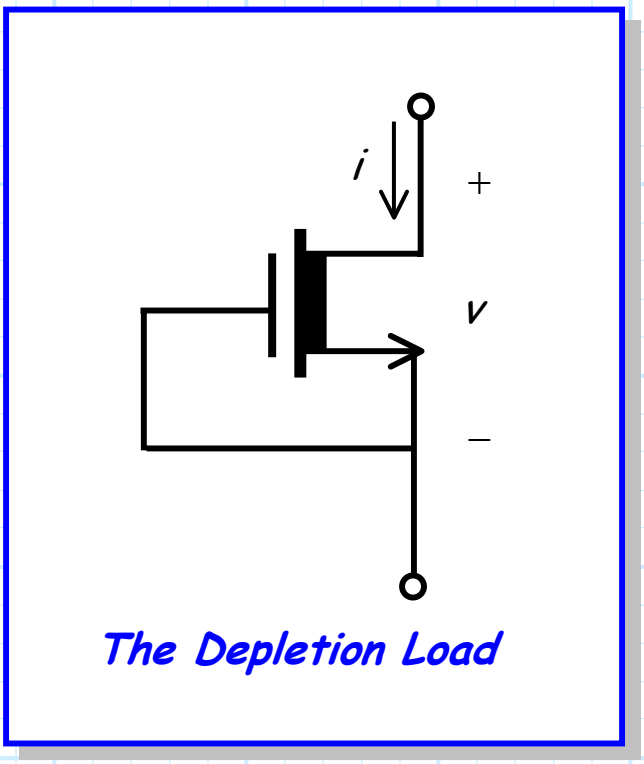
Additionally, there is **one more** problem when implementing NMOS in **integrated circuits**. IC resistors are (relatively) very large and difficult to construct.

→ This problem, though, is easily solved—we replace the **pull-up resistor** with an **active load**.

# The Depletion Load

Say we connect the gate of a **depletion** NMOS to its source—we now have a **two-terminal device**!

This device is called a **depletion load**.




*The Depletion Load*

Since the depletion load is a two-terminal device, its **behavior** is defined by the relationship between the **voltage** $v$ across the device and the **current** $i$ through it.

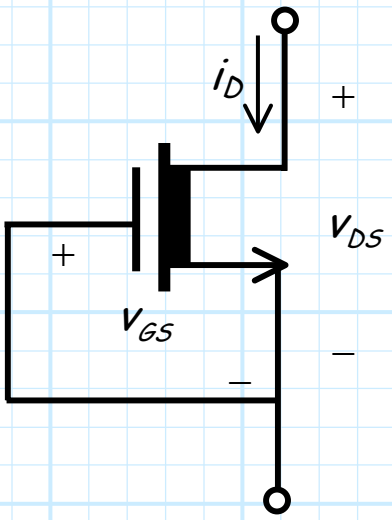
For example, a **resistor** is a two terminal device whose behavior (i.e., its relationship between $i$ and $v$) is defined by **Ohm's Law** ($i = v/R$).

Although the **depletion load** is decidedly **not** a resistor, its $i$-$v$ relationship does have **some** similarities with Ohm's Law.

**Q:** *So what **is** "Ohm's Law" for a **depletion load** (i.e., what is $i = f(v)$)?*

**A:** A result easily found by implementing our knowledge of **depletion** MOSFETs!

For a **depletion load**, we find that:




$$i_D = i$$
$$v_{GS} = 0$$
$$v_{DS} = v$$
$$v_{GS} - V_t = -V_t$$

**Q:** *But since $v_{GS} = 0$, isn't the NMOS device in **cutoff**?*

**A:** **Nope!** Notice that this is a depletion MOSFET, and a depletion MOSFET **will** conduct when $v_{GS} = 0$!

Thus the MOSFET in a depletion load will always be either in: **a)** triode or **b)** saturation.

**a)** Depletion load MOSFET is in **triode** if:

$$v_{DS} < v_{GS} - V_t$$
$$v < 0 - V_t$$
$$v < -V_t$$

Therefore, the **current** will be:

$$i_D = K\left[2(v_{GS} - V_t)v_{DS} - v_{DS}^2\right]$$
$$i = K\left[2(0 - V_t)v - v^2\right]$$
$$i = K\left[-2V_t\, v - v^2\right]$$

**b)** Depletion load MOSFET is in **saturation** if:

$$v_{DS} > v_{GS} - V_t$$
$$v > 0 - V_t$$
$$v > -V_t$$

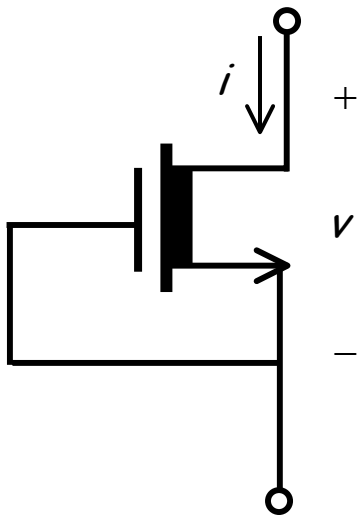
Therefore, the **current** will be:

$$i_D = K\left(v_{GS} - V_t\right)^2 + \frac{v_{DS}}{r_o}$$
$$i = K\left(0 - V_t\right)^2 + \frac{v}{r_o}$$
$$i = K\left(-V_t\right)^2 + \frac{v}{r_o}$$
$$i = K\,V_t^2 + \frac{v}{r_o}$$


where in this case:

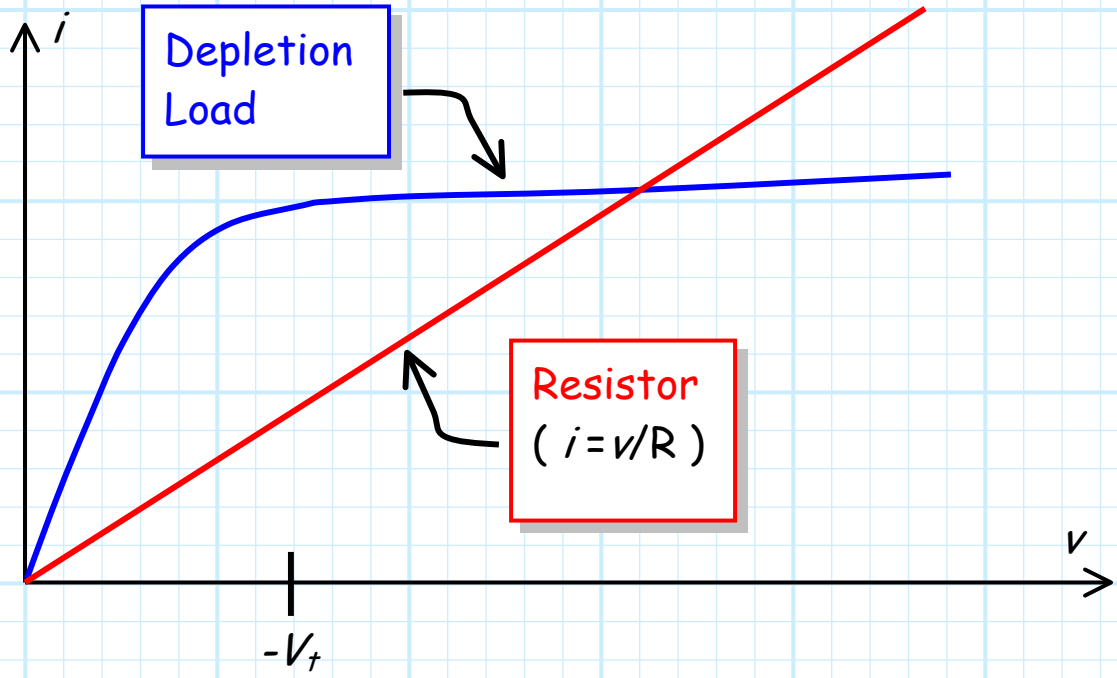
$$r_o = \frac{1}{\lambda K\left(v_{GS} - V_t\right)^2} = \frac{1}{\lambda K\left(0 - V_t\right)^2} = \frac{1}{\lambda\, V_t^2}$$

**Combining** the two results, we find that "Ohm's Law" for a depletion load is:




$$i = \begin{cases} K\left[-2V_t\, v - v^2\right] & \text{if } 0 < v < -V_t \\ K V_t^2 + \dfrac{v}{r_o} & \text{if } v > -V_t \end{cases}$$

**Plotting** this function, we find something like this:

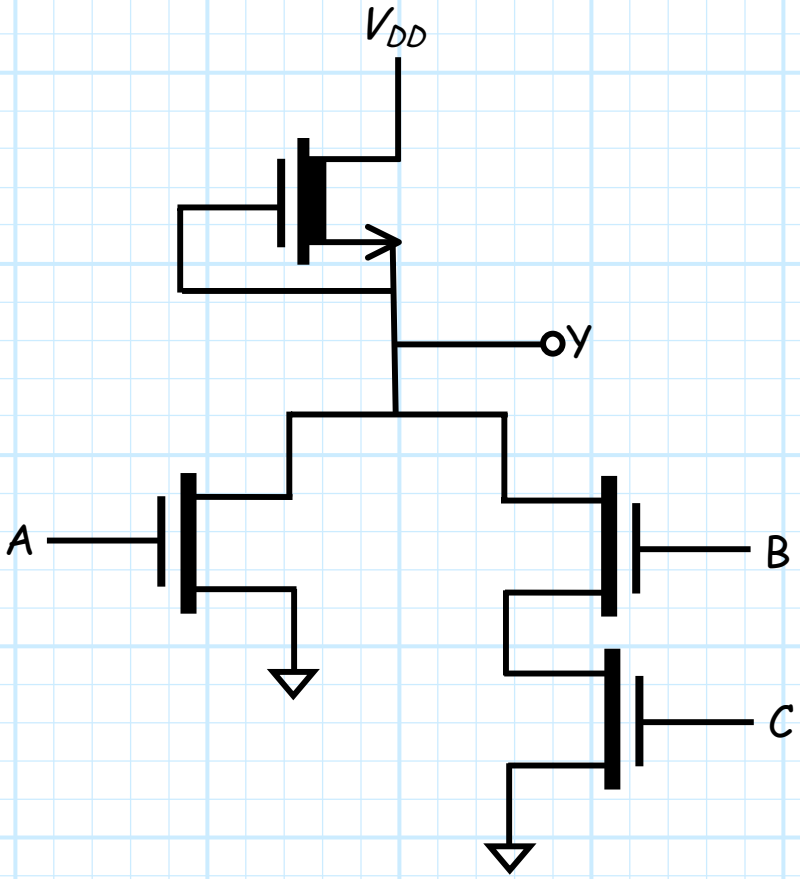


Note that the behavior of a Depletion Load and a resistor are **very different**—however they are precisely the **same** in two key ways:

1. When the voltage across each device (i.e., resistor and depletion load) is **zero**, the current through each device is likewise **zero** (and vice versa!).

2. As the voltage across each device **increases**, the current through each device **increases**.

As a result, we can use a depletion load as the "**pull-up resistor**" in our integrated circuit NMOS logic!

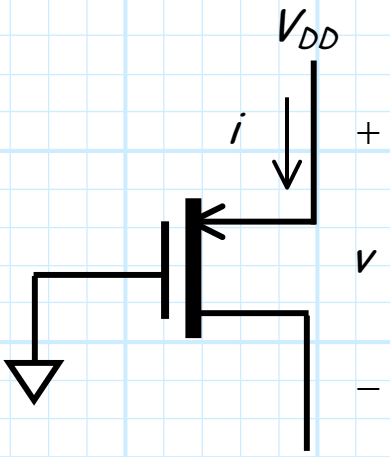


# The Pseudo-NMOS Load

There is another type of active load that is used for NMOS logic, but this load is made from a **PMOS** transistor!

Hence, NMOS logic that uses this load is referred to as **Pseudo NMOS Logic,** since not all of the devices in the circuit will be NMOS (the **load** will be **PMOS**!).

We therefore call this load the "**Pseudo NMOS Load**", since it is the load used in **Pseudo NMOS logic**. But, keep in mind that the **pseudo NMOS load** is made from a **PMOS** device (this can cause great confusion!).




$$i_D = i$$
$$v_{GS} = 0 - V_{DD} = -V_{DD}$$
$$v_{DS} = -v$$
$$v_{GS} - V_t = -(V_{DD} + V_t)$$

***The Pseudo-NMOS Load***

Note that $v_{GS} = -V_{DD} < V_t$, so that the load is **not** in cutoff—it can either be in **saturation or triode**.

The PMOS will be in **triode** if:

$$\begin{aligned} v_{DS} &> v_{GS} - V_t \\ -v &> -\left(V_{DD} + V_t\right) \\ v &< \left(V_{DD} + V_t\right) \end{aligned}$$

In which case the **current** is:

$$\begin{aligned} i_D &= K\left[2\left(v_{GS} - V_t\right)v_{DS} - v_{DS}^2\right] \\ i &= K\left[-2\left(V_{DD} + V_t\right)(-v) - (-v)^2\right] \\ i &= K\left[2\left(V_{DD} + V_t\right)v - v^2\right] \end{aligned}$$

Likewise, the PMOS will be in saturation if:

$$\begin{aligned} v_{DS} &< v_{GS} - V_t \\ -v &< -\left(V_{DD} + V_t\right) \\ v &> \left(V_{DD} + V_t\right) \end{aligned}$$

In which case the **current** is:

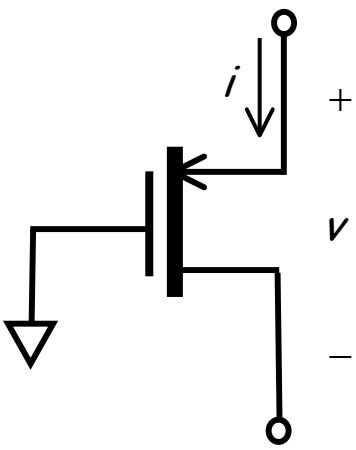
$$i_D = K\left(v_{GS} - V_t\right)^2 - \frac{v_{DS}}{r_o}$$

$$i = K\left(V_{DD} + V_t\right)^2 + \frac{v}{r_o}$$

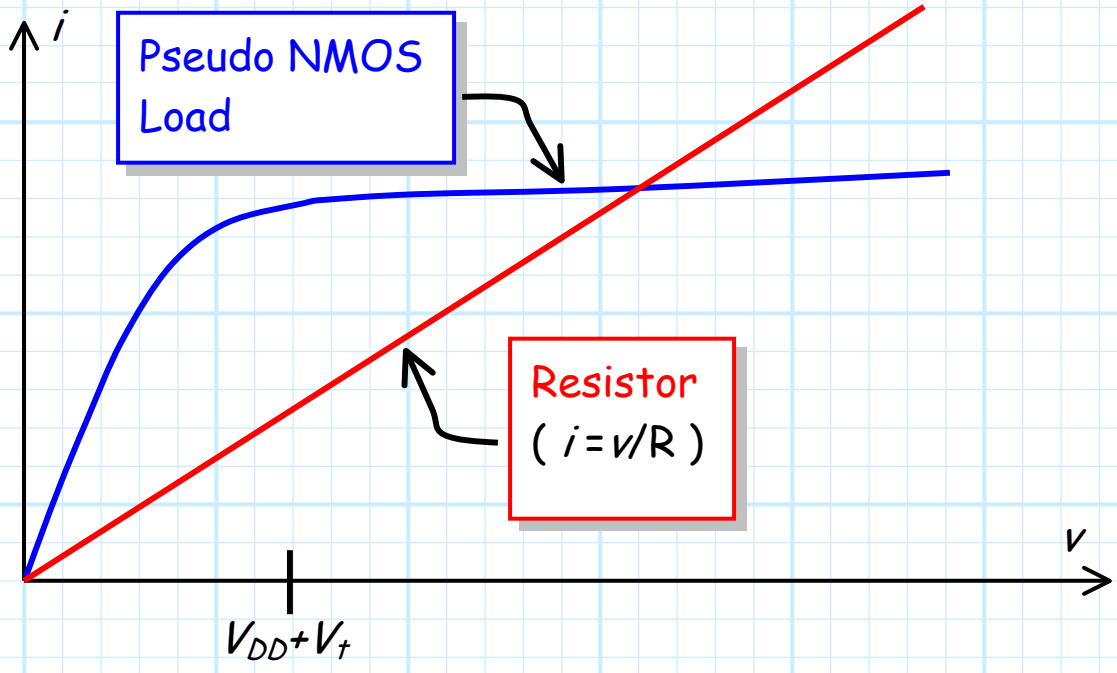
where in this case:

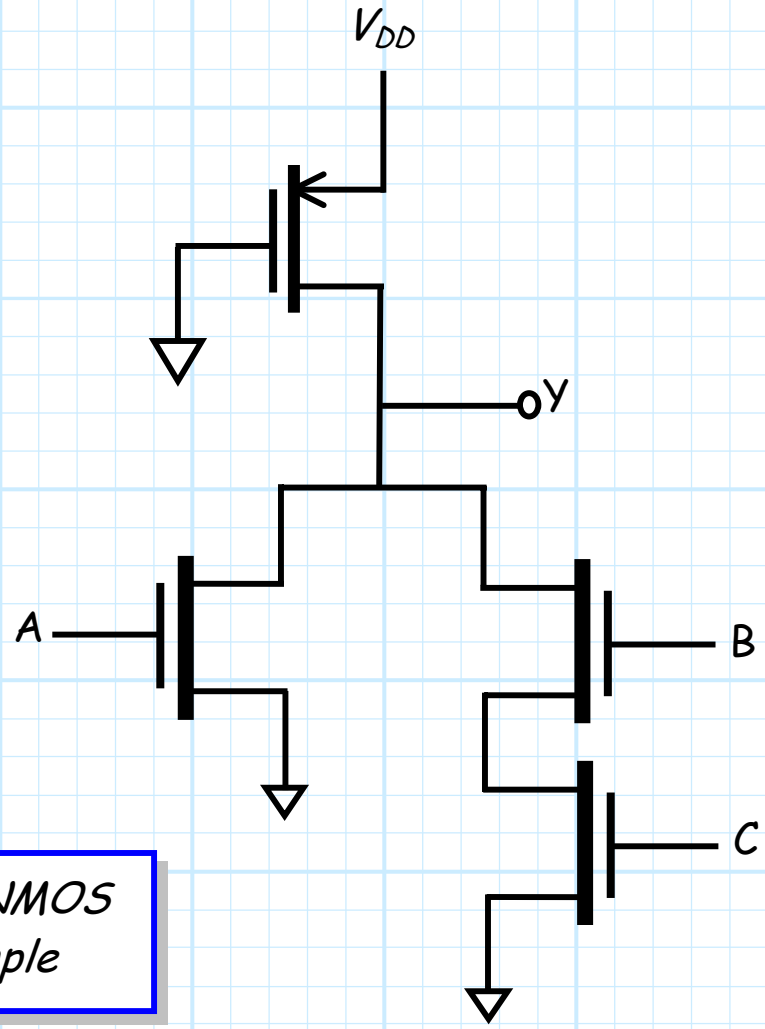
$$r_o = \frac{1}{\lambda K \left(v_{GS} - V_t\right)^2} = \frac{1}{\lambda K \left(V_{DD} + V_t\right)^2}$$

Combining these two results, we find that the pseudo NMOS load behaves very much like the depletion load:




$$i = \begin{cases} K\left[2\left(V_{DD} + V_t\right)v - v^2\right] & \text{if } 0 < v < \left(V_{DD} + V_t\right) \\ K\left(V_{DD} + V_t\right)^2 + \dfrac{v}{r_o} & \text{if } v > \left(V_{DD} + V_t\right) \end{cases}$$






*A Pseudo-NMOS Logic Example*